Laplace Transforms

LAPLACE TRANSFORMS

•In Food Engineering we develop a number of mathematical models that describe the dynamic operation of selected processes.

•Solving such models requires either analytical or numerical integration of the differential equations.

•Laplace transformation is a mathematical tool that converts differential equations to algebraic equations.

• It reduces the effort required to solve the model.

Definition

The laplace transform of a function f(t) is defined as:

$$f(s) = \int_{0}^{\infty} f(t)e^{-st}dt$$

- f(t) is a function depends on time
- f(s) function is the Laplace Transform of f(t)
- Laplace transformations can represented by different symbols.

$$f(s) = L\{f(t)\} = F(s) = \overline{f(s)} = Y(s)$$

Let's apply Laplace transform to f(t) = 1

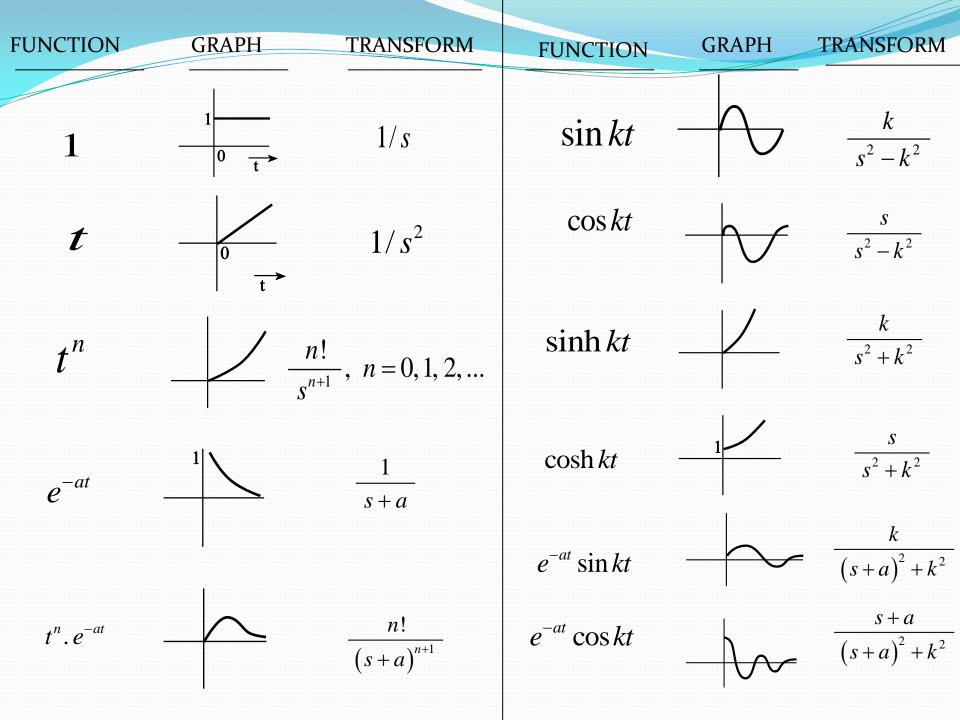
$$f(s) = \int_{0}^{\infty} (1) e^{-st} dt = -\frac{e^{-st}}{s} \Big|_{0}^{\infty} = -0 + \frac{e^{-s^{*}0}}{s} = \frac{1}{s}$$

$$L\{1\} = \frac{1}{s}$$

Therefore the laplace transform of f(t)=1 is:

$$f\{s\} = \frac{1}{s}$$

- In solving differential equations:
 - First apply Laplace transformation
 - Then solve the equations algebraically to obtain Y(s)
 - Finally take the inverse Laplace transform
- Laplace transform tables helps us to convert the functions.



PROPERTIES OF LAPLACE TRANSFORM

1. Time variable is between zero and infinity(o< t < ∞)

2. Laplace transformation is always applied to linear differential equations

3. The laplace transform of the sum of two function is equal to laplace transform of individual functions separately.

L {a $f_1(t)$ + b $f_2(t)$ } = aL { $f_1(t)$ } + bL { $f_2(t)$ } a and b are constants, f_1 and f_2 are the functions.

4. Variable *t* is eliminated by variable *s* during laplace transformation.

Laplace Transform of a Derivative

$$\pounds \{f'(t)\} = sf(s) - f(0)$$

$$\pounds \{f''(t)\} = s^2 f(s) - sf(0) - f'(0)$$

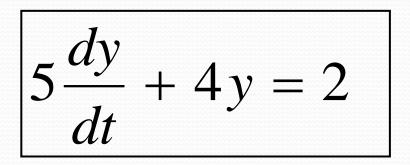
$$\pounds \{\frac{d^n f(t)}{dt^n}\} = s^n f(s) - s^{n-1} f(0) - s^{n-2} f'(0) \dots - f^{n-1}(0)$$

Laplace Transform of an Integral

$$\pounds\left\{\int_{0}^{t} f(t)dt\right\} = \frac{f(s)}{s}$$

How to solve differential equ.?

y = f(t) y(0) = 1 L(y) = Y(s)



- y \rightarrow is a function of t
 - y= 1 @ t=o
 - Laplace transform of function y is equal to Y(s)

 Solve the differential equation above using laplace transforms.

How to solve differential equ.?

$$y = f(t)$$
 $y(0) = 1$ $L(y) = Y(s)$

$$5\frac{dy}{dt} + 4y = 2$$

- Apply laplace transform to each term
- Solve the equations algebraically to obtain Y(s)
- Apply inverse transform to each term
- You may use the Laplace table.

Example Solve the differential equation by Laplace.

$$\frac{d^2 y}{dt^2} + 2\frac{dy}{dt} + y = 1$$

$$y(0) = y'(0) = 0$$

Final and Initial Value Theorem Final and initial value theorem gives information about the process in process control and process dynamics.

$$\lim_{t \to \infty} [f(t)] = \lim_{s \to 0} [s F(s)]$$

FINAL VALUE THEOREM

 It is used to find the steady state value of the function (t=∞)

$$\lim_{t \to 0} [f(t)] = \lim_{s \to \infty} [s F(s)]$$
INITIAL VALUE THEOREM

 It is used to find the initial value of the function at t=o

Examples of Final and Initial Value Theorem

$$Y(s) = \frac{5s+2}{s(5s+4)}$$
$$sY(s) = \frac{5s+2}{(5s+4)}$$

$$\lim_{s \to \infty} sY(s) = \frac{5s+2}{5s+4} = 1$$

Initial value theorem

$$\lim_{s \to 0} sY(s) = \frac{5s+2}{5s+4} = 0.5$$

Final value theorem

EXAMPLE

$$\frac{d^2 y}{dt^2} + 6\frac{dy}{dt} + 8y = 2 \quad y(0) = y'(0) = 0 \circ ODE$$

- Apply laplace transform to each term
- Solve for Y(s)
- Apply the method of partial fractions
- Determine the inverse transform

SOLUTION

$$\frac{d^2 y}{dt^2} + 6\frac{dy}{dt} + 8y = 2 \quad y(0) = y'(0) = 0 \quad \bullet \text{ OD}$$

$$s^{2} Y(s) + 6s Y(s) + 8Y(s) = 2/s$$

$$Y(s) = \frac{2}{s(s+2)(s+4)}$$

$$Y(s) = \frac{1}{4s} + \frac{-1}{2(s+2)} + \frac{1}{4(s+4)}$$
$$y(t) = \frac{1}{4} - \frac{e^{-2t}}{2} + \frac{e^{-4t}}{4}$$

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- Apply laplace transform to each term
- Solve for Y(s)
- Apply the method of partial fractions
- Determine the inverse transform