#### Physics 101: Mechanics Lecture 2

#### **Baris EMRE**

#### Vector vs. Scalar Review

- All physical quantities encountered in this text will be either a scalar or a vector
- □ A **vector** quantity has both magnitude (value + unit) and direction
- □ A **scalar** is completely specified by only a magnitude (value + unit)

# Vector and Scalar Quantities

#### Vectors

- Displacement
- Velocity (magnitude and direction!)
- Acceleration
- Force
- Momentum

#### Scalars:

- Distance
- Speed (magnitude of velocity)
- Temperature
- Mass
- Energy
- Time

To describe a vector we need more information than to describe a scalar! Therefore vectors are more complex!

#### **Important Notation**

#### How to describe vectors:

- The bold font: Vector A is A
- Or an arrow above the vector: A
- In the pictures, we will always show vectors as arrows
- Arrows point the direction
- To describe the magnitude of a vector we will use absolute value sign:  $|\vec{A}|$  or just A,
- Magnitude is always positive, the magnitude of a vector is equal to the length of a vector.



# **Properties of Vectors**

#### Equality of Two Vectors

- Two vectors are equal if they have the same magnitude and the same direction
- Movement of vectors in a diagram
- Any vector can be moved parallel to
   Negative vectors



$$\vec{\mathbf{A}} = -\vec{\mathbf{B}}; \vec{\mathbf{A}} + (-\vec{\mathbf{A}}) = 0$$





# **Adding Vectors**

- When adding vectors, their directions must be taken into account
- Units must be the same
- Geometric Methods
  - Use scale drawings
- Algebraic Methods
  - More convenient



→ S

(b)

#### Adding Vectors Geometrically (Triangle Method)

- Draw a vector with an appropriate length and a coordinate system in the specified direction
- Draw the next vector at the appropriate length and B in the specified direction, according to the coordinate system that is parallel to the coordinate system used for "tail to tail" when the vector ends.
- The result is drawn from the original to the end of the last vector



### Adding Vectors Graphically

When you have many vectors, just keep repeating the process until all are included

The resultant is still drawn from the origin of the first vector to the end of the last vector

#### Adding Vectors Geometrically (Polygon Method)

- Draw the first vector  $\vec{A}$  with the appropriate length and in the direction specified, with respect to a coordinate system
- □ Draw the next vector  $\vec{B}$  with the appropriate length and in the direction specified, with respect to the same coordinate system
- Draw a parallelogram
- The resultant is drawn as a diagonal from the origin

$$\vec{A} + \vec{B} = \vec{B} + \vec{A}$$



#### **Vector Subtraction**

- Special case of vector addition
  - Add the negative of the subtracted vector

 $\vec{\mathbf{A}} - \vec{\mathbf{B}} = \vec{\mathbf{A}} + \left(-\vec{\mathbf{B}}\right)$ 

Continue with standard vector addition procedure



# **Describing Vectors Algebraically**

Vectors: Described by the number, units and direction!



(a)

Vectors: Can be described by their magnitude and direction. For example: Your displacement is 1.5 m at an angle of 30<sup>0</sup>.

Can be described by components? For example: your displacement is *1.28 m* in the positive x direction and *0.75m* in the positive y direction.

#### Components of a Vector

- □ A **component** is a part
- It is useful to use rectangular components
  - These are the projections of the vector along the x- and yaxes

Figure 3.13 **Physics for Scientists and Engineers** 6th Edition, Thomson Brooks/Cole © 2004; Chapter 3

#### **Components of a Vector**



The x-component of a vector is the projection along the x-axis  $\cos \theta = \frac{A_x}{A}$   $A_x = A \cos \theta$ The y-component of a vector is

The y-component of a vector is the projection along the y-axis  $\sin \theta = \frac{A_y}{A}$   $A_y = A \sin \theta$ 

Then,

 $\vec{A} = \vec{A}_x + \vec{A}_y$ 



#### **Unit Vectors**

Components of a vector are vectors

 $\vec{A} = \vec{A}_x + \vec{A}_y$ 

Unit vectors *i*-hat, *j*-hat, *k*-hat

 $\hat{i} \rightarrow x \quad \hat{j} \rightarrow y \quad \hat{k} \rightarrow z$ 

Figure 3.16 **Physics for Scientists and Engineers** 6th Edition, Thomson Brooks/Cole © 2004; Chapter 3 Unit vectors used to specify direction
 Unit vectors have a magnitude of 1
 Then
  $\vec{A} = A_x \hat{i} + A_y \hat{j}$  Magnitude + Sign Unit vector

#### Adding Vectors Algebraically

Consider two vectors

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$
$$\vec{B} = B_x \hat{i} + B_y \hat{j}$$





#### Then

 $\vec{A} + \vec{B} = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$ =  $(A_x + B_x)\hat{i} + (A_y + B_y)\hat{j}$ If  $\vec{C} = \vec{A} + \vec{B} = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j}$ So  $C_x = A_x + B_x$   $C_y = A_y + B_y$ 

# Scalar Product of Two Vectors (dot product)

The scalar product of two vectors is written as \$\vec{A} \cdot \$\vec{B}\$

$$\vec{\mathbf{A}} \cdot \vec{\mathbf{B}} \equiv A B \cos \theta$$

θ is the angle
 between A and B

$$W = F \Delta r \cos \theta = \vec{\mathbf{F}} \cdot \Delta \vec{\mathbf{r}}$$

Figure 7.16 **Physics for Scientists and Engineers** 6th Edition, Thomson Brooks/Cole © 2004; Chapter 7

#### Dot Product

- The dot product says something about how parallel two vectors are.
- The dot product (scalar product) of two vectors can be thought of as the projection of one onto the direction of the other.

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$
$$\vec{A} \cdot \hat{i} = A \cos \theta = A_x$$

Components

 $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$ 

#### Projection of a Vector: Dot Product

- The dot product talks about how parallel two vectors are.
- The dot product of two vectors (scalar multiplication) can be thought of as the reflection of one towards the other.

Components  

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$
  
 $\vec{A} \cdot \hat{i} = A \cos \theta = A_x$ 

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\hat{i} \cdot \hat{j} = 0; \ \hat{i} \cdot \hat{k} = 0; \ \hat{j} \cdot \hat{k} = 0$$
  
 $\hat{i} \cdot \hat{i} = 1; \ \hat{j} \cdot \hat{j} = 1; \ \hat{k} \cdot \hat{k} = 1$ 

#### Vector Product (Cross Product ) $\vec{C} = \vec{A} \times \vec{B}$

- The cross product of two vectors says something about how perpendicular they are.
- Magnitude:

$$\left. \overrightarrow{C} \right| = \left| \overrightarrow{A} \times \overrightarrow{B} \right| = AB \sin \theta$$

- $\theta$  is smaller angle between the vectors
- Cross product of any parallel vectors = zero
- Cross product is maximum for perpendicular vectors
- Cross products of Cartesian unit vectors:

$$\hat{i} \times \hat{j} = \hat{k}; \ \hat{i} \times \hat{k} = -\hat{j}; \ \hat{j} \times \hat{k} = \hat{i}$$
$$\hat{i} \times \hat{i} = 0; \ \hat{j} \times \hat{j} = 0; \ \hat{k} \times \hat{k} = 0$$



#### **Cross Product**

- Direction: C perpendicular to both A and B (right-hand rule)
  - Place A and B tail to tail
  - Right hand, not left hand
  - Four fingers are pointed along the first vector A
  - "sweep" from first vector A into second vector B through the smaller angle between them
  - Your outstretched thumb points the direction of C

First practice

$$\vec{A} \times \vec{B} = \vec{B} \times \vec{A}?$$

Figure 11.2 **Physics for Scientists and Engineers** 6th Edition, Thomson Brooks/Cole © 2004; Chapter 11

$$\vec{A} \times \vec{B} = \vec{B} \times \vec{A}$$
?

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$



# Summary

- Polar coordinates of vector A (A, q)
- □ Cartesian coordinates  $(A_x, A_y)$
- Relations between them:
- Beware of tan 180-degree ambiguity
- **Unit vectors:**  $\mathbf{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$

Addition of vectors: 
$$\vec{C} = \vec{A} + \vec{B} = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j}$$
  
 $C_x = A_x + B_x$   $C_y = A_y + B_y$ 

- **Scalar multiplication of a vector:**  $a\mathbf{A} = aA_x\hat{i} + aA_y\hat{j}$
- Product of two vectors: scalar product and cross product
  - Dot product is a scalar:  $\vec{A} \cdot \vec{B} = AB \cos \theta = A_x B_x + A_y B_y + A_z B_z$
  - Cross product is a vector (  $\perp \vec{A} \text{ and } \vec{B}$ ):  $|\vec{A} \times \vec{B}| = AB \sin \theta$

$$\begin{cases} A_x = A\cos(\theta) \\ A_y = A\sin(\theta) \end{cases}$$
$$\begin{cases} A = \sqrt{\left(A_x\right)^2 + \left(A_y\right)^2} \\ \tan\left(\theta\right) = \frac{A_y}{A_x} \quad \text{or} \quad \theta = \tan^{-1}\left(\frac{A_y}{A_x}\right) \end{cases}$$