## Physics 101: Mechanics Lecture 2

## Baris EMRE

## Vector vs. Scalar Review

$\square$ All physical quantities encountered in this text will be either a scalar or a vector
$\square$ A vector quantity has both magnitude (value + unit) and direction
$\square$ A scalar is completely specified by only a magnitude (value + unit)

## Vector and Scalar Quantities

$\square$ Vectors

- Displacement
- Velocity (magnitude and direction!)
- Acceleration
- Force
- Momentum
$\square$ Scalars:
- Distance
- Speed (magnitude of velocity)
- Temperature
- Mass
- Energy
- Time

To describe a vector we need more information than to describe a scalar! Therefore vectors are more complex!

## Important Notation

$\square$ How to describe vectors:

- The bold font: Vector A is A
- Or an arrow above the vector: $\vec{A}$
- In the pictures, we will always show vectors as arrows
- Arrows point the direction
- To describe the magnitude of a vector we will use absolute value sign: $|\vec{A}|$ or just A ,
- Magnitude is always positive, the magnitude of a vector is equal to the length of a vector.


## Properties of Vectors

$\square$ Equality of Two Vectors

- Two vectors are equal if they have the same magnitude and the same direction
- Movement of vectors in a diagram
- Any vector can be moved parallel to

- Negsativ wridequtber being affected
- Two vectors are negative if they have the same magnitude but are $180^{\circ}$ apart (opposite directions)

$$
\overrightarrow{\mathbf{A}}=-\overrightarrow{\mathbf{B}} ; \overrightarrow{\mathbf{A}}+(-\overrightarrow{\mathbf{A}})=0
$$



## Adding Vectors

$\square$ When adding vectors, their directions must be taken into account
$\square$ Units must be the same
$\square$ Geometric Methods

- Use scale drawings
$\square$ Algebraic Methods
- More convenient



## Adding Vectors Geometrically (Triangle Method)

- Draw a vector with an appropriate length and a coordinate system in the specified direction
- Draw the next vector at the appropriate length and $\bar{B}$ in the specified direction, according to the coordinate system that is parallel to the coordinate system used for "tail to tail" when the vector ends.
- The result is drawn from the original to the end of the last vector



## Adding Vectors Graphically

$\square$ When you have many
vectors, just keep
repeating the process
until all are included
$\square$ The resultant is still drawn from the origin of the first vector to the end of the last
vector

## Adding Vectors Geometrically (Polygon Method)

- Draw the first vector $\vec{A}$ with the appropriate length and in the direction specified, with respect to a coordinate system
- Draw the next vector $\vec{B}$ with the appropriate length and in the direction specified, with respect to the same coordinate system
- Draw a parallelogram
- The resultant is drawn as a diagonal from the origin


$$
\vec{A}+\vec{B}=\vec{B}+\vec{A}
$$

## Vector Subtraction

$\square$ Special case of vector addition

- Add the negative of the subtracted vector

$$
\overrightarrow{\mathbf{A}}-\overrightarrow{\mathbf{B}}=\overrightarrow{\mathbf{A}}+(-\overrightarrow{\mathbf{B}})
$$

$\square$ Continue with standard vector addition procedure


## Describing Vectors Algebraically

Vectors: Described by the number, units and direction!


(a)

Vectors: Can be described by their magnitude and direction. For example: Your displacement is 1.5 m at an angle of $30^{\circ}$.

Can be described by components? For example: your displacement is 1.28 m in the positive $\times$ direction and 0.75 m in the positive y direction.

## Components of a Vector

$\square$ A component is a part
$\square$ It is useful to use rectangular components

- These are the projections of the vector along the $x$ - and $y$ axes

Figure 3.13
Physics for Scientists and
Engineers 6th Edition,
Thomson Brooks/Cole ©
2004; Chapter 3

## Components of a Vector

$\square$ The x-component of a vector is the projection along the x -axis

$$
\cos \theta=\frac{A_{x}}{A} \quad A_{x}=A \cos \theta
$$

The y-component of a vector is the projection along the $y$-axis

$$
\sin \theta=\frac{A_{y}}{A} \quad A_{y}=A \sin \theta
$$

Right angle
$A_{x}>0$

$$
\vec{A}=\vec{A}_{x}+\vec{A}_{y}
$$

$\square$ The components are the legs of the right triangle whose hypotenuse is $A$

$$
\begin{aligned}
& \left\{\begin{array}{l}
A_{x}=A \cos (\theta) \\
A_{y}=A \sin (\theta)
\end{array}\right. \\
& \left\{\begin{array}{l}
|\vec{A}|=\sqrt{\left(A_{x}\right)^{2}+\left(A_{y}\right)^{2}} \\
\tan (\theta)=\frac{A_{y}}{A_{x}} \text { or } \theta=\tan ^{-1}\left(\frac{A_{y}}{A_{x}}\right)
\end{array}\right.
\end{aligned}
$$



## Unit Vectors

$\square$ Components of a vector are vectors

$$
\vec{A}=\vec{A}_{x}+\vec{A}_{y}
$$

$\square$ Unit vectors $i$-hat, $j$-hat, $k$-hat

$$
\hat{i} \rightarrow x \quad \hat{j} \rightarrow y \quad \hat{k} \rightarrow z
$$

Figure 3.16
Physics for Scientists and Engineers 6th Edition, Thomson Brooks/Cole © 2004; Chapter 3
$\square$ Unit vectors used to specify direction
$\square$ Unit vectors have a magnitude of 1
$\square$ Then

$$
\vec{A}=A_{x} \hat{i}+A_{y} \hat{j}
$$

Magnitude + Sign Unit vector

## Adding Vectors Algebraically

$\square$ Consider two vectors

$$
\begin{aligned}
& \vec{A}=A_{x} \hat{i}+A_{y} \hat{j} \\
& \vec{B}=B_{x} \hat{i}+B_{y} \hat{j}
\end{aligned}
$$


(a)

(b)

$$
\square \vec{C}=\overrightarrow{A^{\prime}}+\vec{B}=\left(\Delta_{x}+B_{x}\right) \dot{i}+\left(A_{y}+B_{y}\right)
$$

$\square \mathrm{SO}$

$$
\int_{x}=A_{x}+B_{x}=B_{y}=B_{y}+B_{y}
$$

$$
\begin{aligned}
& \vec{A}+\vec{B}=\left(A_{x}^{\hat{i}}+A_{y} \hat{i}\right)+\left(B_{x}^{\hat{i}}+B_{y} \hat{\boldsymbol{j}}\right) \\
& =\left(A_{x}+B_{x}\right) \dot{i}_{i}^{\hat{i}}\left(A_{y}+B_{y}\right) \dot{i}^{\hat{i}}
\end{aligned}
$$

## Scalar Product of Two Vectors (dot product)

$\square$ The scalar product of two vectors is written as $\overrightarrow{\mathbf{A}} \cdot \overrightarrow{\mathbf{B}}$

Figure 7.16
Physics for Scientists and
Engineers 6th Edition,
Thomson Brooks/Cole © 2004; Chapter 7
$\overrightarrow{\mathbf{A}} \cdot \overrightarrow{\mathbf{B}} \equiv A B \cos \theta$

- $\theta$ is the angle between $A$ and $B$
$W=F \Delta r \cos \theta=\overrightarrow{\mathbf{F}} \cdot \Delta \overrightarrow{\mathbf{r}}$


## Dot Product

- The dot product says something about how parallel two vectors are.
$\square$ The dot product (scalar product) of two vectors can be thought of as the projection of one onto the direction of the other.

$$
\begin{aligned}
& \vec{A} \cdot \vec{B}=A B \cos \theta \\
& \vec{A} \cdot \hat{i}=A \cos \theta=A_{x}
\end{aligned}
$$

$\square$ Components

$$
\vec{A} \cdot \vec{B}=A_{x} B_{x}+A_{y} B_{y}+A_{z} B_{z}
$$

## Projection of a Vector: Dot Product

- The dot product talks about how parallel two vectors are.
- The dot product of two vectors (scalar multiplication) can be

$$
\begin{aligned}
& \hat{i} \cdot \hat{j}=0 ; \hat{i} \cdot \hat{k}=0 ; \hat{j} \cdot \hat{k}=0 \\
& \hat{i} \cdot \hat{i}=1 ; \hat{j} \cdot \hat{j}=1 ; \hat{k} \cdot \hat{k}=1
\end{aligned}
$$ thought of as the reflection of one towards the other.

- Comnnnents

$$
\begin{aligned}
& \vec{A} \cdot \vec{B}=A B \cos \theta \\
& \vec{A} \cdot \hat{i}=A \cos \theta=A_{x}
\end{aligned}
$$

$$
\vec{A} \cdot \vec{B}=A_{x} B_{x}+A_{y} B_{y}+A_{z} B_{z}
$$

## Vector Product (Cross Product ) <br> $$
\vec{C}=\vec{A} \times \vec{B}
$$

- The cross product of two vectors says something about how perpendicular they are.
- Magnitude:

$$
|\vec{C}|=|\vec{A} \times \vec{B}|=A B \sin \theta
$$

- $\theta$ is smaller angle between the vectors
- Cross product of any parallel vectors = zero
- Cross product is maximum for perpendicular vectors
- Cross products of Cartesian unit vectors:

$$
\begin{aligned}
& \hat{i} \times \hat{j}=\hat{k} ; \hat{i} \times \hat{k}=-\hat{j} ; \hat{j} \times \hat{k}=\hat{i} \\
& \hat{i} \times \hat{i}=0 ; \hat{j} \times \hat{j}=0 ; \hat{k} \times \hat{k}=0
\end{aligned}
$$




## Cross Product

- Direction: C perpendicular to both A and B (right-hand rule)
- Place A and B tail to tail
- Right hand, not left hand
- Four fingers are pointed along the first vector A
- "sweep" from first vector A into second vector B through the smaller angle between them
- Your outstretched thumb points the direction of C
- First practice

$$
\vec{A} \times \vec{B}=\vec{B} \times \vec{A} ?
$$

$$
\vec{A} \times \vec{B}=\vec{B} \times \vec{A} ?
$$

Figure 11.2
Physics for Scientists and
Engineers 6th Edition,
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2004; Chapter 11

$$
\vec{A} \times \vec{B}=-\vec{B} \times \vec{A}
$$


(a)


## Summary

$\square$ Polar coordinates of vector $\mathrm{A}(A, q)$
$\square$ Cartesian coordinates $\left(A_{x}, A_{y}\right)$

- Relations between them:
- Beware of tan 180-degree ambiguity

$$
\begin{aligned}
& \left\{\begin{array}{l}
A_{x}=A \cos (\theta) \\
A_{y}=A \sin (\theta)
\end{array}\right. \\
& \left\{\begin{array}{l}
A=\sqrt{\left(A_{x}\right)^{2}+\left(A_{y}\right)^{2}} \\
\tan (\theta)=\frac{A_{y}}{A_{x}} \quad \text { or } \theta=\tan ^{-1}\left(\frac{A_{y}}{A_{x}}\right)
\end{array}\right.
\end{aligned}
$$

$\square$ Unit vectors: $\mathbf{A}=A_{x} \hat{i}+A_{y} \hat{j}+A_{z} \hat{k}$
$\square$ Addition of vectors:

$$
\begin{aligned}
& \vec{C}=\vec{A}+\vec{B}=\left(A_{x}+B_{x}\right) \hat{i}+\left(A_{y}+B_{y}\right) \hat{j} \\
& C_{x}=A_{x}+B_{x} \quad C_{y}=A_{y}+B_{y}
\end{aligned}
$$

$\square$ Scalar multiplication of a vector: $a \mathbf{A}=a A_{x} \hat{i}+a A_{y} \hat{j}$
$\square$ Product of two vectors: scalar product and cross product

- Dot product is a scalar: $\vec{A} \cdot \vec{B}=A B \cos \theta=A_{x} B_{x}+A_{y} B_{y}+A_{z} B_{z}$
- Cross product is a vector $(\perp \vec{A}$ and $\vec{B})$ : $\quad|\vec{A} \times \vec{B}|=A B \sin \theta$

