

# **FEEDBACK CONTROL SYSTEMS**

LECTURE NOTES-7/12

## Stability

A linear time invariant system is stable if natural response approaches to zero as time goes to infinity.

A linear time invariant system is unstable if the natural response grows without bound as time approaches infinity

A linear time invariant system is marginally stable if the natural response neither decays nor grows but remains constant or oscillates as time approaches to infinity

A system is stable if every bounded input yields a bounded output.

We call this statement the bounded input bounded output (BIBO) stability definition of stability

- a. A system is stable if every bounded input yields a bounded output
- b. A system is unstable if any bounded input yields an unbounded output.

Poles at lhp yields pure exponential decay then negative real part which means  
Stable systems have closed-loop transfer function with poles only in the left half-plane

## Routh-Hurwitz Criterion:

Find the number of poles without the coordinates

$$\frac{N(s)}{a_4s^4 + a_3s^3 + a_2s^2 + a_1s + a_0}$$

$s^4$	$a_4$	$a_2$	$a_0$
$s^3$	$a_3$	$a_1$	$0$
$s^2$	$\frac{-\begin{vmatrix} a_4 & a_2 \\ a_3 & a_1 \end{vmatrix}}{a_3} = b_1$	$\frac{-\begin{vmatrix} a_4 & a_2 \\ a_3 & 0 \end{vmatrix}}{a_3} = b_2$	$\frac{-\begin{vmatrix} a_4 & 0 \\ a_3 & 0 \end{vmatrix}}{a_3} = 0$
$s^1$	$\frac{-\begin{vmatrix} a_3 & a_1 \\ b_1 & b_2 \end{vmatrix}}{b_1} = c_1$	$\frac{-\begin{vmatrix} a_3 & 0 \\ b_1 & 0 \end{vmatrix}}{b_1} = 0$	$\frac{-\begin{vmatrix} a_3 & 0 \\ b_1 & 0 \end{vmatrix}}{b_1} = 0$
$s^0$	$\frac{-\begin{vmatrix} b_1 & b_2 \\ c_1 & 0 \end{vmatrix}}{c_1} = d_1$	$\frac{-\begin{vmatrix} b_1 & 0 \\ c_1 & 0 \end{vmatrix}}{c_1} = d_1$	$\frac{-\begin{vmatrix} b_1 & 0 \\ c_1 & 0 \end{vmatrix}}{c_1} = d_1$

**PROBLEM:** Make the Routh table for the system

$$\frac{1000}{s^3 + 10s^2 + 31s + 1030}$$

$s^3$	1	31	0
$s^2$	1	103	0
$s^1$	$\frac{-\begin{vmatrix} 1 & 31 \\ 1 & 103 \end{vmatrix}}{1} = -72$	$\frac{-\begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix}}{1} = 0$	$\frac{-\begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix}}{1} = 0$
$s^0$	$\frac{-\begin{vmatrix} 1 & 103 \\ -72 & 0 \end{vmatrix}}{-72} = 103$	$\frac{-\begin{vmatrix} 1 & 0 \\ -72 & 0 \end{vmatrix}}{-72} = 0$	$\frac{-\begin{vmatrix} 1 & 0 \\ -72 & 0 \end{vmatrix}}{-72} = 0$

Third degree polynomial means 3 poles

Two rows change sign means 2 in rhp and 1 in lhp

Number of roots in rhp = number of sign change at first column

## Routh-Hurwitz Special Cases:

**Case 1:** Zero only in the first column

$$T(s) = \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3}$$

$s^5$	1	3	5
$s^4$	2	6	3
$s^3$	$\epsilon$	$7/2$	0
$s^2$	$(6\epsilon-7)/\epsilon$	2	0
$s^1$	$(42\epsilon-49-6\epsilon^2)/(12\epsilon-14)$	0	0
$s^0$	3	0	0

$s^5$	1	+	+
$s^4$	2	+	+
$s^3$	$\epsilon$	+	-
$s^2$	$(6\epsilon-7)/\epsilon$	-	+
$s^1$	$(42\epsilon-49-6\epsilon^2)/(12\epsilon-14)$	+	+
$s^0$	3	+	+

**Example:** Determine the stability of the closed loop transfer function

$$T(s) = \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3}$$

$D(s) = s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3$

$s^5$	3	6	2
$s^4$	5	3	1
$s^3$	4.2	1.4	0
$s^2$	1.33	1	0
$s^1$	-1.75	0	0
$s^0$	1	0	0

2 rhp  
3 lhp

## Case 2: Entire Row is Zero

$$T(s) = \frac{10}{s^5 + 27 + 6s^3 + 42s^2 + 8s + 56}$$

$s^5$	1	6	8
$s^4$	1	6	8
$s^3$	1	3	0

$$P(s) = s^4 + 6s^2 + 8$$

$$\frac{dP(s)}{ds} = 4s^3 + 12s$$

$s^5$	1	6	8
$s^4$	1	6	8
$s^3$	1	3	0
$s^2$	3	8	0
$s^1$	1/3	0	0
$s^0$	8	0	0

**Example:** For the transfer function given below; obtain the number of poles at right half-plane, left- half plane and  $j\omega$  axis.

$$T(s) = \frac{10}{s^8 + s^7 + 12s^6 + 22s^5 + 39s^4 + 59s^3 + 48s^2 + 38s + 20}$$

$s^5$	1	12	39	48	20
$s^7$	1	22	59	38	0
$s^6$	-1	-2	1	2	0
$s^5$	1	3	2	0	0
$s^4$	1	3	2	0	0
$s^3$	2	3	0	0	0

$s^5$	1	12	39	48	20
$s^7$	1	22	59	38	0
$s^6$	-1	-2	1	2	0
$s^5$	1	3	2	0	0
$s^4$	1	3	2	0	0
$s^3$	2	3	0	0	0
$s^2$	3	4	0	0	0
$s^1$	1/3	0	0	0	0
$s^0$	4	0	0	0	0

$s^8$  to  $s^4$ , two sign change  $\rightarrow$  2 rhp and 2lhp

No sign change from  $s^4$  to  $s^0$   $\rightarrow$  No rhp  
Then 4 poles on  $j\omega$ -axis

$$P(s) = s^4 + 3s^2 + 2$$

$$\frac{dP(s)}{ds} = 4s^3 + 6s$$



**Example:** Find the number of poles

$$T(s) = \frac{100}{s^4 + 6s^3 + 11s^2 + 6s + 200}$$

$s^4$	1	11	200
$s^3$	1	1	0
$s^2$	1	20	0
$s^1$	-19	0	0
$s^0$	20	0	0

**Example:** Find the number of poles

$$T(s) = \frac{10}{2s^5 + 3s^4 + 2s^3 + 3s^2 + 2s + 1}$$

$s^5$	2	2	2
$s^4$	3	3	1
$s^3$	$\epsilon$	$4/3$	0
$s^2$	$(3^\epsilon - 4)/\epsilon$	1	0
$s^1$	$(12\epsilon - 16 - 32\epsilon^2)/(9^\epsilon - 12)$	0	0
$s^0$	1	0	0

$s^5$	1	3	3
$s^4$	2	2	2
$s^3$	2	2	0
$s^2$	$\epsilon$	2	0
$s^1$	$(2\epsilon - 4)/\epsilon$	0	0
$s^0$	2	0	0