

## Curves and Parametrization

$$\vec{R} = x(t)\hat{x} + y(t)\hat{y} + z(t)\hat{z} \quad a \leq t \leq b$$

$$\vec{v}(t) = \frac{d\vec{R}}{dt}$$

Arc length = s

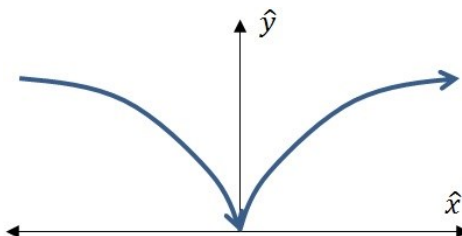
$$s = \int_{t_1}^{t_2} |\vec{v}(t)| dt$$

$$= \int_{t_1}^{t_2} \left| \frac{d\vec{R}}{dt} \right| dt \quad \int_{t_1}^{t_2} v(t) dt$$

$$= \int_{t_1}^{t_2} v(t) dt$$

$$v(t) = |\vec{v}(t)| = \left| \frac{d\vec{R}}{dt} \right|$$

Ex.



$$\vec{R} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$x = t^3$$

$$y = t^2$$

$$z = 0$$

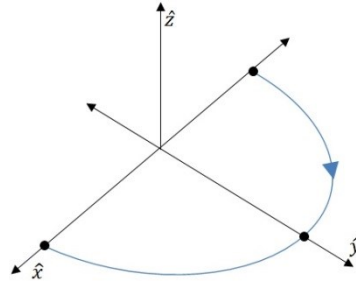
$$\vec{R} = t^3\hat{x} + t^2\hat{y} \quad -\infty \leq t \leq +\infty$$

$$\vec{v}(t) = 3t^2\hat{x} + 2t\hat{y}$$

$$|\vec{v}(t)| = 0 @ t = 0 \quad \begin{matrix} x = t^3 = 0 \\ y = t^2 = 0 \\ z = 0 \end{matrix}$$

Not smooth at  $t = 0$   
 Piecewise smooth for  $t > 0$  &  $t < 0$

Ex.



$$\begin{aligned}
 \vec{R}_1 &= \sin(t) \cdot \hat{x} + \cos(t) \hat{y} + 0\hat{z} & t: -\frac{\pi}{2} \rightarrow +\frac{\pi}{2} \\
 \vec{v}_1 &= \frac{d\vec{R}_1}{dt} \\
 v_1 = |\vec{v}_1| &= \left| \frac{d\vec{R}_1}{dt} \right| \\
 & \begin{matrix} t \\ -\frac{\pi}{2} \\ 0 \\ \frac{\pi}{2} \end{matrix} & \begin{matrix} x=\sin(t) & y=\cos(t) & z=0 \end{matrix} \\
 x^2 + y^2 &= 1 \\
 \vec{R}_2 &= (t-1)\hat{x} + \sqrt{2t-t^2}\hat{y} + 0\hat{z} & t: 0 \rightarrow 2 \\
 \vec{v}_1 &= \frac{d\vec{R}_1}{dt} \\
 v_1 = |\vec{v}_1| &= \left| \frac{d\vec{R}_1}{dt} \right| \\
 & \begin{matrix} t \\ 0 \\ 1 \\ 2 \end{matrix} & \begin{matrix} x=(t-1) & y=\sqrt{2t-t^2} & z=0 \end{matrix} \\
 x^2 + y^2 &= 1 \\
 \vec{R}_3 &= t\sqrt{2-t^2}\hat{x} + (1-t^2)\hat{y} + 0\hat{z} & t: -1 \rightarrow 1 \\
 \vec{v}_1 &= \frac{d\vec{R}_1}{dt} \\
 v_1 = |\vec{v}_1| &= \left| \frac{d\vec{R}_1}{dt} \right| \\
 & \begin{matrix} t \\ -1 \\ 0 \\ 1 \end{matrix} & \begin{matrix} x=t\sqrt{2-t^2} & y=(1-t^2) & z=0 \end{matrix} \\
 x^2 + y^2 &= 1
 \end{aligned}$$

Ex

Parametrize the intersection of two surfaces

$$3x + 2y + z = 4 \quad \text{a plane}$$

$$x^2 + y^2 = 4 \quad \text{An elliptic cylinder}$$

Choose

$$x = 2\cos(t)$$

$$y = \sin(t)$$

$\Rightarrow$

$$z = 4 - 3x - 2y$$

$$z = 4 - 6\cos(t) - 2\sin(t)$$

$$\vec{R} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$2\cos(t) \cdot \hat{x} + \sin(t)\hat{y} + (4 - 6\cos(t) - 2\sin(t))\hat{z}$$

$$\overrightarrow{dR} = dt \cdot \{-2\sin(t) \cdot \hat{x} + \cos(t)\hat{y} + (6\sin(t) - 2\cos(t))\hat{z}\}$$

Ex

Parametrize the intersection of two surfaces

$$xy + z = 1$$

$$x^2 + y + z = 2$$

Choose

$$x = t$$

$\Rightarrow$

$$z = 1 - xy = 1 - ty$$

$\Rightarrow$

$$t^2 + y + 1 - ty = 2$$

$\Rightarrow$

$$y = \frac{1 - t^2}{1 - t} = 1 + t$$

$\Rightarrow$

$$z = 1 - xy = 1 - t \cdot (1 + t)$$

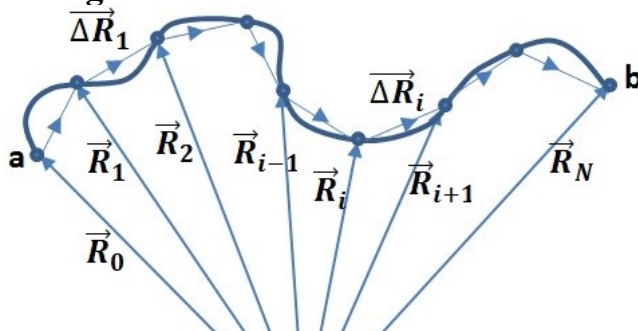
$$z = 1 - t - t^2$$

$$\vec{R} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$t\hat{x} + (1 + t)\hat{y} + (1 - t - t^2)\hat{z}$$

$$\overrightarrow{dR} = dt \cdot \{1 \cdot \hat{x} + 1 \cdot \hat{y} + (-1 - 2t) \cdot \hat{z}\}$$

Arc length:  $s$



$$s = \sum_{i=1}^N \left| \frac{\Delta \vec{R}_i}{\Delta t_i} \right| \cdot \Delta t_i$$

$$s = \int_a^b \left| \frac{d\vec{R}_i}{dt_i} \right| dt$$

$$s = \int_a^b |\vec{v}| dt$$

$$s = \int_a^b v dt$$

$$\overline{\Delta \vec{R}}_i = \vec{R}_{i+1} - \vec{R}_i$$

Assume  $\vec{R} = x\hat{x} + f(x)\hat{y}$

$$\frac{d\vec{R}}{dx} = 1.\hat{x} + f'(x).\hat{y}$$

$$ds = \left| \frac{d\vec{R}}{dt} \right| dt = \left| \frac{d\vec{R}dx}{dxdt} \right| dt = \left| \frac{d\vec{R}}{dx} \right| dx$$

$$\left| \frac{d\vec{R}}{dx} \right| = |1.\hat{x} + f'(x).\hat{y}| = \sqrt{1 + (f'(x))^2}$$

$$ds = \sqrt{1 + (f'(x))^2} . dx$$

Ex: Find arclength s for the circular helix:  $\vec{R} = a\cos(t)\hat{x} + a\sin(t)\hat{y} + bt\hat{z}$  between (a,0,0) and (a,0,2πb).

$$x = a\cos(t)$$

$$y = a\sin(t)$$

$$z = bt$$

$$x^2 + y^2 = a^2$$

$$\vec{v} = \frac{d\vec{R}}{dt} = -a\sin(t)\hat{x} + a\cos(t)\hat{y} + b\hat{z}$$

$$|\vec{v}| = v = \sqrt{(-a\sin(t))^2 + (a\cos(t))^2 + b^2}$$

$$v = \sqrt{a^2 + b^2}$$

$$s = \int_{P_{start}}^{P_{stop}} v dt = \int_0^{2\pi} \sqrt{a^2 + b^2} dt = 2\pi\sqrt{a^2 + b^2}$$

Type equation here.

$$ds = |d\vec{R}| = |d\vec{l}| = dl$$

$$ds = |d\vec{l}| = |(1.dr)\hat{r} + (1.d\phi)\hat{\phi} + (1.dz)\hat{z}|$$

$$ds = \left| \left( 1. \frac{dr}{dt} \right) \hat{r} + \left( r. \frac{d\phi}{dt} \right) \hat{\phi} + \left( 1. \frac{dz}{dt} \right) \hat{z} \right| dt$$

$$ds = |\vec{dl}| = \sqrt{\left(1 \cdot \frac{dr}{dt}\right)^2 + \left(r \cdot \frac{d\varphi}{dt}\right)^2 + \left(1 \cdot \frac{dz}{dt}\right)^2} dt$$

$$ds = |\vec{dl}| = |(1 \cdot dR)\hat{R} + (R \cdot d\theta)\hat{\theta} + (R\sin\theta \cdot d\varphi)\hat{\varphi}|$$

$$ds = |\vec{dl}| = \left| \left(1 \cdot \frac{dR}{dt}\right)\hat{R} + \left(R \cdot \frac{d\theta}{dt}\right)\hat{\theta} + \left(R\sin\theta \cdot \frac{d\varphi}{dt}\right)\hat{\varphi} \right| dt$$

$$ds = |\vec{dl}| = \sqrt{\left(1 \cdot \frac{dR}{dt}\right)^2 + \left(R \cdot \frac{d\theta}{dt}\right)^2 + \left(R\sin\theta \cdot \frac{d\varphi}{dt}\right)^2} dt$$

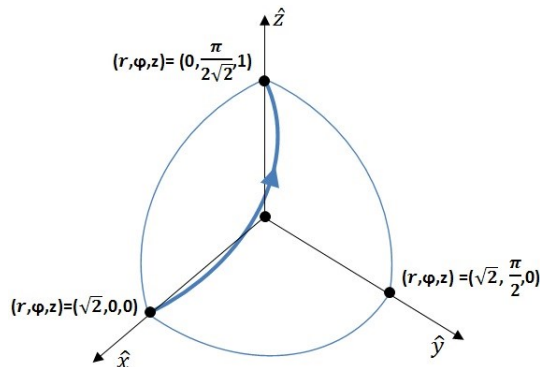
Ex: Describe the curve and find the arc length for  $t: 0 \rightarrow \frac{\pi}{2}$  where

$$r(t) = \sqrt{2} \cos(t)$$

Solution

$$\varphi = \frac{\pi}{2}$$

$$z = \sin(t)$$



See that

$$r^2 + 2z^2 = 2 \quad (\text{Ellipsoid in 3D})$$

$$x^2 + y^2 + 2z^2 = 2$$

$$s = \int_a^b |\vec{v}| dt = \int_a^b ds = \int_a^b \sqrt{\left(1 \cdot \frac{dr}{dt}\right)^2 + \left(r \cdot \frac{d\varphi}{dt}\right)^2 + \left(1 \cdot \frac{dz}{dt}\right)^2} dt$$

$$s = \int_0^{\frac{\pi}{2}} \sqrt{(1 \cdot 2\sin(t))^2 + \left(2\cos(t) \cdot \frac{1}{\sqrt{2}}\right)^2 + (1 \cdot \cos(t))^2} dt$$

$$s = \frac{\pi}{\sqrt{2}} \text{ units}$$

### Arc length parametrization

$$ds = v(t) dt \quad \text{general parametrization}$$

$$ds = v(s) ds \quad t = s \text{ (arc length parametrization)}$$

$$\Rightarrow v(s) = 1 = \text{constant}$$

$\Rightarrow$  Arc length parametrized curves are traversed at constant speed of  $v(s) = 1$

Ex: Parametrize circular helix in arc length parametrization

$$\begin{aligned} \vec{R} &= a\cos(t)\hat{x} + a\sin(t)\hat{y} + bt\hat{z} \\ \vec{v} = \frac{d\vec{R}}{dt} &= -a\sin(t)\hat{x} + a\cos(t)\hat{y} + b\hat{z} \\ |\vec{v}| = v &= \sqrt{(-a\sin(t))^2 + (a\cos(t))^2 + b^2} \\ v &= \sqrt{a^2 + b^2} \\ s &= \int_{Pstart}^{Pstop} v dt = \int_0^t \sqrt{a^2 + b^2} dt = t\sqrt{a^2 + b^2} \\ \Rightarrow t &= \frac{s}{\sqrt{a^2 + b^2}} \\ \Rightarrow \vec{R} &= a\cos\left(\frac{s}{\sqrt{a^2 + b^2}}\right)\hat{x} + a\sin\left(\frac{s}{\sqrt{a^2 + b^2}}\right)\hat{y} + b\left(\frac{s}{\sqrt{a^2 + b^2}}\right)\hat{z} \end{aligned}$$

### LINE INTEGRAL

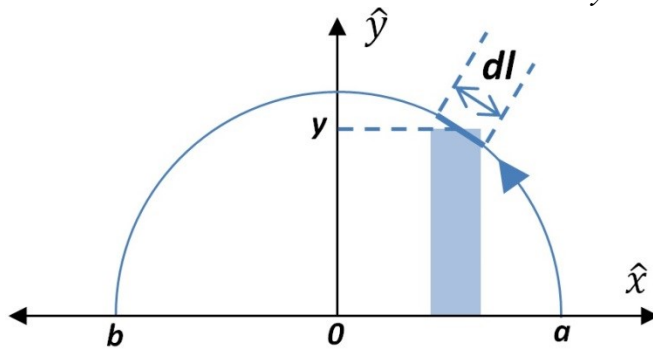
Length of C=

$$\int_C ds = \int_a^b dl = \int_a^b \left| \frac{d\vec{R}}{dt} \right| dt$$

In general,

$$\int_C f(\vec{R}(t)) dl = \int_a^b f(\vec{R}(t)) \left| \frac{d\vec{R}}{dt} \right| dt$$

Ex: Calculate the moment of half circle about y=0



$$M = \int_C y \cdot dl$$

$$x = a\cos(t) \quad y = a\sin(t)$$

$$\vec{R} = x\hat{x} + y\hat{y}$$

$$\vec{R} = a\cos(t)\hat{x} + a\sin(t)\hat{y}$$

$$\frac{d\vec{R}}{dt} = -a\sin(t)\hat{x} + a\cos(t)\hat{y}$$

$$t: 0 \rightarrow \pi$$

$$\left| \frac{d\vec{R}}{dt} \right| = |-a\sin(t)\hat{x} + a\cos(t)\hat{y}|$$

$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{(-a\sin(t)\hat{x} + a\cos(t)\hat{y}) \cdot (-a\sin(t)\hat{x} + a\cos(t)\hat{y})}$$

$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{a^2(\sin^2(t) + \cos^2(t))} = a$$

$$dl = \left| \frac{d\vec{R}}{dt} \right| dt = a \cdot dt$$

$$M = \int_C y \cdot dl = \int_0^\pi a\sin(t) \cdot a \cdot dt = 2a^2$$

Alternative parametrization

$$x = x = t \quad y = \pm\sqrt{a^2 - x^2} \quad x: -a \rightarrow a$$

$$\vec{R} = x\hat{x} + y\hat{y}$$

$$\vec{R} = x\hat{x} + \sqrt{a^2 - x^2}\hat{y}$$

$$\frac{d\vec{R}}{dx} = 1\hat{x} - \frac{x}{\sqrt{a^2 - x^2}}\hat{y}$$

$$t: 0 \rightarrow \pi$$

$$\left| \frac{d\vec{R}}{dt} \right| = \left| 1\hat{x} - \frac{x}{\sqrt{a^2 - x^2}}\hat{y} \right|$$

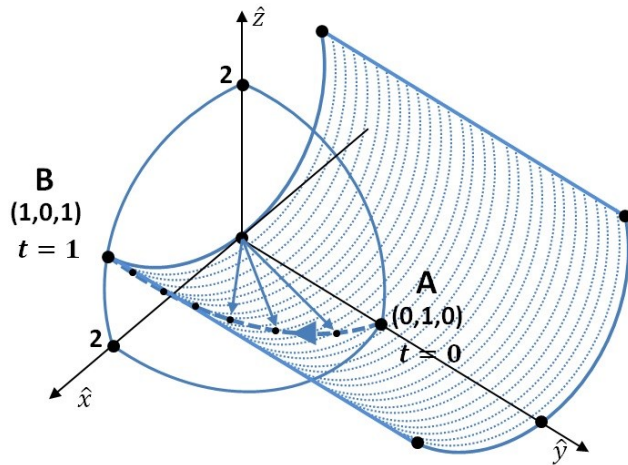
$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{\left(1\hat{x} - \frac{x}{\sqrt{a^2 - x^2}}\hat{y}\right) \cdot \left(1\hat{x} - \frac{x}{\sqrt{a^2 - x^2}}\hat{y}\right)}$$

$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{\left(1 + \frac{x^2}{a^2 - x^2}\right)} = \sqrt{\left(\frac{a^2}{a^2 - x^2}\right)}$$

$$dl = \left| \frac{d\vec{R}}{dt} \right| dt = \sqrt{\left(\frac{a^2}{a^2 - x^2}\right)} \cdot dx = \frac{a}{\sqrt{a^2 - x^2}}$$

$$M = \int_C y \cdot dl = \int_{-a}^a \sqrt{a^2 - x^2} \cdot \frac{a}{\sqrt{a^2 - x^2}} \cdot dx = 2a^2$$

Ex: Assume a wire with density  $\rho(x, y, z) = xy \left(\frac{\text{grams}}{\text{m}^2}\right)$ . Find the mass of the wire which is padded on the contour from  $(0, 1, 0)$  to  $(1, 0, 1)$  if the contour is obtained by the intersection of the surfaces  $z = 2 - x^2 - 2y^2$  and  $z = x^2$ .



$$x = t$$

$$y = \sqrt{1 - t^2}$$

$$z = t^2$$

$t$	$0$	$\rightarrow$	$1$
$x$	$0$		$1$
$y$	$1$		$0$
$z$	$0$		$1$
	A		B

$$\vec{R} = x\hat{x} + y\hat{y} + z\hat{z} = t\hat{x} + \sqrt{1 - t^2}\hat{y} + t^2\hat{z}$$

$$\frac{d\vec{R}}{dx} = 1\hat{x} - \frac{t}{\sqrt{1 - t^2}}\hat{y} + 2t\hat{z} \quad t: 0 \rightarrow 1$$

$$\left| \frac{d\vec{R}}{dt} \right| = \left| \frac{d\vec{R}}{dx} = 1\hat{x} - \frac{t}{\sqrt{1 - t^2}}\hat{y} + 2t\hat{z} \right|$$

$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{\left(1\hat{x} - \frac{t}{\sqrt{1 - t^2}}\hat{y} + 2t\hat{z}\right) \cdot \left(1\hat{x} - \frac{t}{\sqrt{1 - t^2}}\hat{y} + 2t\hat{z}\right)}$$

$$\left| \frac{d\vec{R}}{dt} \right| = \sqrt{1 + \frac{t^2}{1 - t^2} + 4t^2} = \sqrt{\frac{1 + 4t^2 - 4t^4}{1 - t^2}}$$

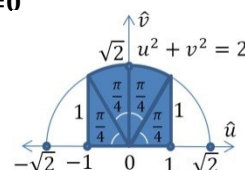
$$dl = \left| \frac{d\vec{R}}{dt} \right| dt = \sqrt{\frac{1 + 4t^2 - 4t^4}{1 - t^2}} \cdot dt$$

$$\text{Mass } m = \int_C \rho(x, y, z) \cdot dl = \int_C xy \cdot dl = \int_{t=0}^1 t \cdot \sqrt{1 - t^2} \cdot dl$$

$$m = \int_{t=0}^1 t \cdot \sqrt{1 - t^2} \cdot \sqrt{\frac{1 + 4t^2 - 4t^4}{1 - t^2}} dt = \int_{t=0}^1 \sqrt{1 + 4t^2 - 4t^4} \cdot t \cdot dt$$

$$t^2 = k \quad t dt = \frac{dk}{2} \Rightarrow m = \int_{k=0}^1 \sqrt{1 + 4k - 4k^2} \frac{dk}{2} = \int_{k=0}^1 \sqrt{2 - (2k - 1)^2} \frac{dk}{2}$$

$$m = \int_{v=-1}^1 \sqrt{2 - u^2} \frac{du}{4} = \frac{1}{4} \cdot 2 \cdot \left(\frac{\pi}{4} + \frac{1}{2}\right)$$





## Stoke's Theorem

$$\int_S \nabla \times \vec{A} \cdot \vec{dS} = \oint_C \vec{A} \cdot \vec{dl}$$

### Null Identities

$$1) \nabla \times (\nabla V) = \mathbf{0}$$

The curl of a gradient of a scalar field is identically zero.

Proof: Consider an arbitrary surface S bounded by a closed contour C.

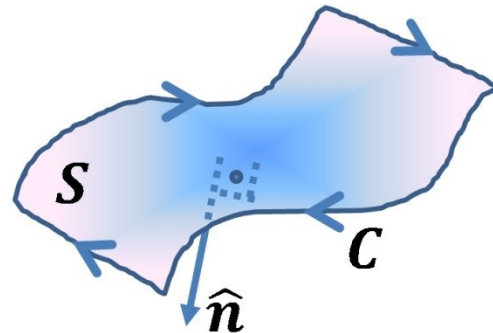
$$\int_S \nabla \times (\nabla V) \cdot \vec{dS} = \oint_C \nabla V \cdot \vec{dl} \quad (\text{By Stoke's Theorem})$$

$$\nabla V \cdot \hat{l}$$

is the directional derivative i.e., the derivative of  $V$  in the  $\hat{l}$  direction

$$= \oint_C \nabla V \cdot \hat{l} dl = \oint_C \frac{dV}{dl} dl$$

$$\oint_C dV = V \Big|_{P_1}^{P_1=P_2} = V(P_2) - V(P_1) = 0$$



⇒

$$\oint_C \nabla V \cdot \vec{dl} = \int_S \nabla \times (\nabla V) \cdot \vec{dS} = 0 \quad \forall S$$

⇒

$$\nabla \times (\nabla V) = 0$$

If a vector is curl-free (i.e., if the curl a vector field is 0), then it can be expressed as a gradient of a vector field.

Such curl-free vector fields are called  
"irrotational" or "conservative".

Ex: In electrostatics,

$$\vec{E} = \nabla V \quad \Leftrightarrow \quad \nabla \times \vec{E} = \mathbf{0}$$

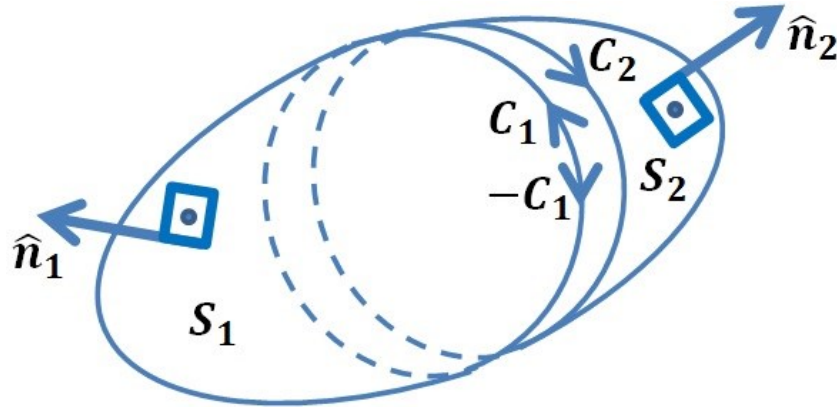
$\vec{E}$  : Electric field intensity vector

$\vec{E}$  : Conservative, Irrotational

$$2) \nabla \cdot (\nabla \times \vec{A}) = 0$$

**Proof:**

Split the closed surface  $S$  into two open surfaces  $S_1$  and  $S_2$  with common rim  $C$ :



By Divergence Theorem:

$$S = S_1 \cup S_2$$

$$\vec{dS}_1 = \hat{n}_1 dS \quad \vec{dS}_2 = \hat{n}_2 dS$$

$$-\oint_{C_1} \vec{A} \cdot d\vec{l}_1 = \oint_{-C_1} \vec{A} \cdot d\vec{l}_1 = \oint_{C_2} \vec{A} \cdot d\vec{l}_2$$

$$\begin{aligned} \int_V \nabla \cdot (\nabla \times \vec{A}) dV &= \oint_S \nabla \times \vec{A} \cdot d\vec{S} \\ &= \int_{S_1} \nabla \times \vec{A} \cdot d\vec{S} + \int_{S_2} \nabla \times \vec{A} \cdot d\vec{S} \end{aligned}$$

Using Stoke's Theorem

$$\int_V \nabla \cdot (\nabla \times \vec{A}) dV = \oint_{C_1} \vec{A} \cdot d\vec{l}_1 + \oint_{C_2} \vec{A} \cdot d\vec{l}_2$$

$$\int_V \nabla \cdot (\nabla \times \vec{A}) dV = -\oint_{C_2} \vec{A} \cdot d\vec{l}_2 + \oint_{C_2} \vec{A} \cdot d\vec{l}_2$$

$$\int_V \nabla \cdot (\nabla \times \vec{A}) dV = 0 \quad \forall V$$

$$\nabla \cdot (\nabla \times \vec{A}) = 0$$

If a vector field is divergenceless, then it is called as Solenoidal Field and It can be expressed as the curl of an another vector:

$\vec{B}$ : Magnetic Flux Density

$\vec{A}$ : Vector Potential

$$\nabla \cdot \vec{B} = 0 \Leftrightarrow \vec{B} = \nabla \times \vec{A}$$

### Field Classification and Helmholtz Theorem

- |    |   |                                |
|----|---|--------------------------------|
| 1) | Static electric field in a charge free region         |                                |
|    | Solenoidal  | Irrotational                   |
|    | $\nabla \cdot \vec{F} = 0$                            | $\nabla \times \vec{F} = 0$    |
| 2) | Steady magnetic field in a current carrying conductor |                                |
|    | Solenoidal  | Not Irrotational               |
|    | $\nabla \cdot \vec{F} = 0$                            | $\nabla \times \vec{F} \neq 0$ |
| 3) | Static electric field in a charged region             |                                |
|    | Not Solenoidal  | Irrotational                   |
|    | $\nabla \cdot \vec{F} \neq 0$                         | $\nabla \times \vec{F} = 0$    |
| 4) | Time-varying electric field in a charged region       |                                |
|    | Not Solenoidal  | Not Irrotational               |
|    | $\nabla \cdot \vec{F} \neq 0$                         | $\nabla \times \vec{F} \neq 0$ |

In general, a vector field  $\vec{F}$  can be decomposed into its solenoidal ( $\vec{F}_s$ ) and irrotational ( $\vec{F}_i$ ) parts as:

$$\begin{aligned} \vec{F} &= \vec{F}_s + \vec{F}_i \\ \nabla \cdot \vec{F}_s &= 0 & \nabla \times \vec{F}_i &= 0 \\ \nabla \times \vec{F}_s &\neq 0 & \nabla \cdot \vec{F}_i &\neq 0 \end{aligned}$$

Thus,

$$\begin{aligned} \nabla \cdot \vec{F} &= \nabla \cdot (\vec{F}_s + \vec{F}_i) \\ &= \nabla \cdot \vec{F}_s + \nabla \cdot \vec{F}_i \\ &= \nabla \cdot \vec{F}_i \\ \nabla \times \vec{F} &= \nabla \times (\vec{F}_s + \vec{F}_i) \\ &= \nabla \times \vec{F}_s + \nabla \times \vec{F}_i \\ &= \nabla \times \vec{F}_s \end{aligned}$$

According to Helmholtz Theorem, a vector field is determined if both its divergence and its curl are specified everywhere in the space of interest:

$$\begin{aligned} \nabla \cdot \vec{F} &\rightarrow \text{Measure of strength of flow sources (scalar sources)} \\ \nabla \times \vec{F} &\rightarrow \text{Measure of strength of vortex sources (vector sources)} \\ &\Rightarrow \vec{F} = \vec{F}_s + \vec{F}_i \\ &\vec{F} = \nabla \times \vec{A} + (-\nabla V) \end{aligned}$$

where

$V$ : Scalar Potential

$\vec{A}$ : Scalar Potential

$$\begin{aligned} \nabla \cdot \vec{F} &= \nabla \cdot (\vec{F}_s + \vec{F}_i) \\ \nabla \cdot \vec{F} &= \nabla \cdot (-\nabla V + \nabla \times \vec{A}) \\ \nabla \cdot \vec{F} &= -\nabla \cdot (\nabla V) + \nabla \cdot (\nabla \times \vec{A}) \\ \nabla \cdot \vec{F} &= -\nabla \cdot (\nabla V) = -\nabla \cdot \nabla(V) \\ \nabla \cdot \vec{F} &= -\nabla^2 V \neq 0 \end{aligned}$$

$$\begin{aligned} \nabla \times \vec{F} &= \nabla \times (\vec{F}_s + \vec{F}_i) \\ \nabla \times \vec{F} &= \nabla \times (-\nabla V + \nabla \times \vec{A}) \\ \nabla \times \vec{F} &= -\nabla \times (\nabla V) + \nabla \times (\nabla \times \vec{A}) \\ \nabla \times \vec{F} &= \nabla \times (\nabla \times \vec{A}) \\ \nabla \times \vec{F} &= \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \neq 0 \end{aligned}$$

Knowing  $\nabla \cdot \vec{F}$

One can solve for  $V$  using  $\nabla \cdot \vec{F} = -\nabla^2 V$

Knowing  $\nabla \times \vec{F}$

One can solve for  $\vec{A}$  using  $\nabla \times \vec{F} = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$

Having obtained  $V$  and  $\vec{A}$  one can write  $\vec{F}$  as

$$\vec{F} = \nabla \times \vec{A} + (-\nabla V)$$

## Static Electric Field

Electric field intensity is defined as the force per unit charge that a very small stationary test charge experiences when it is placed in a region where an electric field exists.

$$\vec{E} = \lim_{q \rightarrow 0} \frac{\vec{F}}{q}$$

$$\vec{F} = q\vec{E}$$

$$[\vec{F}] = \text{Newton}$$

$$[\vec{E}] = \frac{\text{Newton}}{\text{Coulomb}} = \frac{\text{Volt}}{\text{m}} \quad \text{Electric Field Intensity}$$

### Fundamental Postulates of Electrostatics in free space (Differential Form)

$$\nabla \cdot \vec{E} = \frac{\rho_v}{\epsilon_0} \quad \text{Divergence of Electric Field}$$

$$\nabla \times \vec{E} = 0 \quad \text{Curl of Electric Field}$$

(Remember Helmholtz Theorem)

$$[\rho_v] = \frac{\text{Coulomb}}{\text{m}^3} \quad \text{Free Volume Charge Density}$$

$$\epsilon_0 = \frac{1}{36\pi} \cdot 10^{-9}$$

$$[\epsilon_0] = \frac{\text{Farad}}{\text{m}} \quad \text{Dielectric constant for free space}$$

### Notes:

- Static electric fields are always irrotational but they are solenoidal at points where  $\rho_v = 0$ ,
- All other relations in electrostatics can be obtained using these fundamental postulates,
- These postulates are independent of the chosen coordinate system.