Lecture 13: Gram-Schmidt Process

Elif Tan

Ankara University

Definition (Orthonormal Basis)

Let V be an inner product space and $S = \{u_1, u_2, ..., u_n\}$ be an ordered basis for the vector space V. S is called an orthonormal basis if the followings are satisfied:

$$(i) \forall i \neq j, \langle u_i, u_j \rangle = 0$$

$$(ii)$$
 $i = 1, ..., n, \langle u_i, u_i \rangle = 1.$

To obtain this orthonormal basis we use a method which is called Gram-Schmidt process.

Theorem

Let $T = \{w_1, w_2, ..., w_n\}$ be an orthonormal basis for the inner product space V and $v \in V$. Then

$$v = c_1 \odot w_1 \oplus c_2 \odot w_2 \oplus \cdots \oplus c_n \odot w_n$$

where

$$c_i = \langle v, w_i \rangle$$
.

We determine the coordinates of the vector by using inner product instead of solving linear system!

Theorem (Gram-Schmidt Process)

Let V be an inner product space and $\{0\} \neq W < V$ and dimW = m. Then there exists an orthonormal basis $T = \{w_1, w_2, \dots, w_n\}$ for W.

Sketch of the proof: Let $S = \{u_1, u_2, \dots, u_m\}$ be any basis for W.

- $v_1 := u_1$
- $v_2=u_2-rac{\langle u_2,v_1
 angle}{\langle v_1,v_1
 angle}\odot v_1$ (Note that $v_1\perp v_2$)
- $v_3 = u_3 \frac{\langle u_3, v_1 \rangle}{\langle v_1, v_1 \rangle} \odot v_1 \frac{\langle u_3, v_2 \rangle}{\langle v_2, v_2 \rangle} \odot v_2$ (Note that $v_1 \perp v_2, v_1 \perp v_3, v_2 \perp v_3$)
- Similarly, we obtain m-orthogonal vectors as

$$v_m = u_m - \odot v_1 - \frac{\langle u_m, v_2 \rangle}{\langle v_2, v_2 \rangle} \odot v_2 - \cdots - \frac{\langle u_m, v_{m-1} \rangle}{\langle v_{m-1}, v_{m-1} \rangle} \odot v_{m-1}.$$

• Thus, we obtain an orthogonal set $K = \{v_1, v_2, \dots, v_m\}$. Since K is a linear independent set in m-dimensional vector space, K is a basis for W.

Now, if we let

$$w_i = \frac{v_i}{\|v_i\|}$$

for $i=1,2,\ldots,m$, then $T=\{w_1,w_2,\ldots,w_m\}$ is an orthonormal basis for W.

The matrix of the inner product with respect to the ordered orthogonal basis K is

$$B = \begin{bmatrix} \langle v_1, v_1 \rangle & 0 & \cdots & 0 \\ 0 & \langle v_2, v_2 \rangle & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \langle v_n, v_n \rangle \end{bmatrix}.$$

The matrix of the inner product with respect to the ordered orthonormal basis T is

$$I_m = \left[egin{array}{cccc} 1 & 0 & \cdots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \cdots & 0 & 1 \end{array}
ight].$$

For
$$u, v \in V$$
, we have $\begin{bmatrix} u \end{bmatrix}_T = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix}$ and $\begin{bmatrix} v \end{bmatrix}_T = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$.

If we use the orthonormal basis \overline{T} , then

$$\langle u, v \rangle = \begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix} I_m \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

$$= a_1b_1 + a_2b_2 + \cdots + a_mb_m$$

which is the standard inner product.

References

- 1) B. Kolman and D.R. Hill. Elemantery Linear Algebra with Applications. Pearson I.E. (9th Edition)
- 2) L.Spence, A. Insel, S. Friedberg. Elemantery Linear Algebra A Matrix Aproach. Pearson I.E. (2nd Edition)