# **ENE 503 – Computational Fluid Dynamics**

### **WEEK 3: DIFFERENTIAL EQUATIONS**

#### **DIFFERENTIAL EQUATIONS:**

#### Ordinary differential equation:

- Ordinary differential equation (ODE): an equation which, other than the one independent variable x and the dependent variable y, also contains derivatives from y to x. General form

$$F(x,y,y',y'' \dots y^{(n)}) = 0$$

here n is the highest order derivative and the order of the equation is determined by the order n of the

- A partial differential equation (PDE) has two or more independent variables. A PDE with two independent variables has the following form:

$$F\left(x, y, z, \frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}, \frac{\partial^2 z}{\partial x^2}, \frac{\partial^2 z}{\partial x \partial y}, \frac{\partial^2 z}{\partial y^2}, \ldots\right) = 0$$

with z=z(x,y).

- the order of the highest order partial derivative in the equation determines the order here

#### • A general partial differential equation in coordinates x and y:

$$a\frac{\partial^2 \varphi}{\partial x^2} + b\frac{\partial^2 \varphi}{\partial x \partial y} + c\frac{\partial^2 \varphi}{\partial y^2} + d\frac{\partial \varphi}{\partial x} + e\frac{\partial \varphi}{\partial y} + f\varphi + g = 0$$

> where the coefficients *a*, *b*, *c*, *d*, *e*, *f* and *g* are in general functions of the dependent variable,  $\varphi$  and the independent variables *x*, and *y*.

- > Any solution to the above equation represents a surface in space
- The first derivatives of the above equation are continuous functions of the x and y. The total differentials:

$$d\varphi_{x} = \frac{\partial \varphi_{x}}{\partial x} dx + \frac{\partial \varphi_{x}}{\partial y} dy = \frac{\partial^{2} \varphi}{\partial x^{2}} dx + \frac{\partial^{2} \varphi}{\partial x \partial y} dy$$
$$d\varphi_{y} = \frac{\partial \varphi_{y}}{\partial x} dx + \frac{\partial \varphi_{y}}{\partial y} dy = \frac{\partial^{2} \varphi}{\partial x \partial y} dx + \frac{\partial^{2} \varphi}{\partial y^{2}} dy$$

> The original differential equation can be expressed as

$$a\frac{\partial^2 \varphi}{\partial x^2} + b\frac{\partial^2 \varphi}{\partial x \partial y} + c\frac{\partial^2 \varphi}{\partial y^2} = -d\frac{\partial \varphi}{\partial x} - e\frac{\partial \varphi}{\partial y} - f\varphi - g = h$$

The last three equations above form of a system of three linear equations with three unknowns,  $\frac{\partial^2 \varphi}{\partial x^2}$ ,  $\frac{\partial^2 \varphi}{\partial x \partial y}$ , and  $\frac{\partial^2 \varphi}{\partial y^2}$ . The matrix solution can be provided as below:

$$\begin{bmatrix} a & b & c \\ dx & dy & dz \\ 0 & dx & dy \end{bmatrix} \begin{bmatrix} \frac{\partial^2 \varphi}{\partial x^2} \\ \frac{\partial^2 \varphi}{\partial x \partial y} \\ \frac{\partial^2 \varphi}{\partial y^2} \end{bmatrix} = \begin{bmatrix} h \\ d\varphi_x \\ d\varphi_y \end{bmatrix}$$

by using Cramer's rule

$$\frac{\partial^2 \varphi}{\partial x^2} = \frac{\begin{vmatrix} h & b & c \\ d\varphi_x & dy & 0 \\ d\varphi_y & dx & dy \end{vmatrix}}{\begin{vmatrix} a & b & c \\ dx & dy & 0 \\ 0 & dx & dy \end{vmatrix}}$$
$$\frac{\partial^2 \varphi}{\partial x \partial y} = \frac{\begin{vmatrix} a & b & h \\ dx & d\varphi_x & 0 \\ 0 & d\varphi_y & dy \end{vmatrix}}{\begin{vmatrix} a & b & c \\ dx & dy & 0 \\ 0 & dx & dy \end{vmatrix}}$$
$$\frac{\partial^2 \varphi}{\partial y^2} = \frac{\begin{vmatrix} a & b & h \\ dx & d\varphi_x & 0 \\ 0 & dx & dy \end{vmatrix}}{\begin{vmatrix} a & b & c \\ dx & dy & 0 \\ 0 & dx & dy \end{vmatrix}}$$

The second order derivatives if the dependent variables along the characteristics when these derivatives are indeterminant. The denominator of last three equations above must be zero.

 $\begin{vmatrix} a & b & c \\ dx & dy & 0 \\ 0 & dx & dy \end{vmatrix} = 0$ 

This equation can be written as

$$a\left(\frac{dy}{dx}\right)^2 - b\left(\frac{dy}{dx}\right) + c = 0$$

The slope of the above equation can be determined as:

$$\frac{dy}{dx} = \frac{b \pm \sqrt{b^2 - 4ac}}{2a}$$

- Characterization depends on the roots of the higher order terms (second order terms):
  - Hyperbolic nature when  $b^2 4ac > 0$
  - Parabolic nature when  $b^2 4ac > 0$
  - Elliptic behavior when b2 4ac < 0

## • Origin of the terms:

- The "elliptic," "parabolic," or "hyperbolic terms are used to label these equations is simply a direct analogy with the case for conic sections.
- > The general equation for a conic section from analytic geometry is:

where if

- $-b^2 4ac > 0$  the conic is a hyperbola.
- $b^2 4ac = 0$  the conic is a parabola.
- $b^2 4ac > 0$  the conic is an ellipse.

## **References:**

1. Aksel, M.H., 2016, "Notes on Fluids Mechanics", Vol. 1, METU Publications

2. Versteeg H.K., and W. Malalasekera V., 1995, "Computational Fluid Dynamics: The Finite Volume Method", Longman Scientific & Technical, ISBN 0-582-21884-5