ENE 505 – Applied Computational Fluid Dynamics in Renewable Energy Technologies

WEEK 8: TURBULENCE MODELS

TURBULENCE MODELS:

RANS based Turbulence Models

For turbulent, incompressible and Newtonian viscous fluid, the Reynoldsaveraged Navier–Stokes equation is given by:

$$\rho \frac{D\overline{u}_{i}}{Dt} = -\frac{\partial \overline{p}}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[\mu \left(\frac{\partial \overline{u}_{i}}{\partial x_{j}} + \frac{\partial \overline{u}_{j}}{\partial x_{i}} - \frac{2}{3} \delta_{ij} \frac{\partial \overline{u}_{i}}{\partial x_{i}} \right) \right] + \frac{\partial}{\partial x_{j}} \left(-\rho \overline{u_{i}} u_{j} \right)$$

Where ρ is the fluid density, $\overline{u_i}$ is the time averaged velocity, u_j is the deviation from the time averaged velocity, \overline{p} is the time averaged pressure, μ is the dynamic viscosity of the fluid, $-\rho \overline{u_i u_j}$ is the Reynold's stress tensor, which appears on the right-hand side of the time-averaged Navier–Stokes equations as a result of time averaging to Navier–stokes equations.

> The temporal and spatial co-ordinates correspond to t and x_j , respectively. In an eddy-viscosity model, the Reynolds stress is assumed to be proportional to the mean velocity gradients, with the constant of proportionality being the turbulent viscosity, μ_t . This assumption is known as the Boussinesq eddy-viscosity hypothesis, and provides the following expression for the Reynolds stresses [1]

$$-\rho \overline{u_i u_j} = \frac{2}{3} \rho k \delta_{ij} + \mu_t \left(\frac{\partial \overline{u_i}}{\partial \overline{x_j}} + \frac{\partial \overline{u_j}}{\partial x_j} \right) + \frac{2}{3} \mu_t \frac{\partial \overline{u_j}}{\partial x_j} \delta_{ij}$$

where *k* is the turbulent kinetic energy expressed as:

$$k = \frac{1}{2} \overrightarrow{u_i u_j}$$

• Standard k-epsilon Model

- The standard k-ε turbulence model is based on transport equations for turbulent kinetic energy k and its dissipation rate,ε, and it is firstly developed by Launder and Spalding [2].
- The turbulence kinetic energy, k and its rate of dissipation, ε are obtained from the following transport equations due to [2]

$$\rho \frac{Dk}{Dt} = \frac{\partial}{\partial x_i} \left[\left(\mu + \frac{\mu_i}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right] + G_k - \rho \varepsilon$$
$$\rho \frac{D\varepsilon}{Dt} = \frac{\partial}{\partial x_i} \left[\left(\mu + \frac{\mu_i}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_i} \right] + C_{1\varepsilon} \frac{\varepsilon}{k} G_k - C_{2\varepsilon} \rho \frac{\varepsilon^2}{k}$$

where, μ_t is the eddy viscosity, $C_{1\epsilon}$ and $C_{2\epsilon}$ are constants in the sense that they are not changed between calculations. σ_k and σ_{ϵ} are the turbulent Prandtl numbers for *k* and ϵ , respectively. The default values for these coefficients are given as follows: $C_{1\epsilon} = 1.44$, $C_{2\epsilon} = 1.92$, $C_{\mu} = 0.09$, $\sigma_k = 1.0$, and $\sigma_{\epsilon} = 1.0$. G_k represents the generation of turbulent kinetic energy due to the mean velocity gradients, calculated in a manner consistent with the Boussinesg hypothesis.

• The RNG k-epsilon Model

Further development and Improvement from the standard model has been done by Yakhot et al. [3] and is based on the renormalized (RNG) group theory. An additional sink term is suggested; over the standard k-ε turbulence model, in the turbulence dissipation equation to account for non-equilibrium strain rates and employs different values for various model coefficients. The equation of k remains the same and the dissipation equation ε is modified to include the additional sink term:

$$\frac{C_{\mu}\eta^{3}(1\!-\!\eta/\eta_{0})}{1\!+\!\beta\eta^{3}}\frac{\varepsilon^{3}}{k}$$

• The k-omega Model

The k-ω model is based on Wilcox [4]. It compromises modifications for low Reynolds number effects, compressibility and shear flow spreading. It is characterized by the turbulent kinetic energy and the frequency, ω = k / ε, where ε is the rate of dissipation of k. The turbulence viscosity can be expressed as:

$$\mu_t = C_{\mu} \frac{\rho k}{\omega}$$

where the turbulent kinetic energy, k, and the specific dissipation rate, ω , are obtained from the following transport equations:

$$\frac{\partial \rho k}{\partial t} + \frac{\partial \left(\rho \overline{u_i} k\right)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_i}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + P - \rho \omega k$$
$$\frac{\partial \rho \omega}{\partial t} + \frac{\partial \left(\rho \overline{u_i} k\right)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_i}{\sigma_w} \right) \frac{\partial \omega}{\partial x_j} \right] + \gamma \frac{\omega}{k} - \beta \rho \frac{\omega^2}{C_{\mu}}$$

References:

1. Hinze, O. (1975) Turbulence. New York, McGraw-Hill Publishing Co.

2. Launder BE, Spalding DB. Mathematical Models of Turbulence. Academic Press: London, 1972.

3. Yakhot V, Orszag SA, Thangham S, Gatski TB, Speziale CG. Development of turbulence models for shear flows

by a double expansion technique. Physics of Fluids 1992; 4(7): 1510–1520.

4. Wilcox, D. (1998), Turbulence modeling for CFD, California: DCW Industries, Inc., La Canada.